

DeDop – Inland Water Case Study Amazon river



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Overview of the ACA-DDP Project

The ACA-DDP project is part of SEOM (Scientific Exploitation of Operational Missions). In this Project, isardSAT and Brockmann Consult, together with a group of scientists in a larger consortium, **have developed "DeDop"** (for delay-Doppler), **an open source tool to allow the processing of delay-Doppler altimetry data**.

Being open source and distributed online, the tool allows the user to select input data, choose and run processing options, and immediately query and view the results. This introduces a new paradigm in the processing of altimetry data, allowing a much more direct and immediate interaction with the processor in comparison to the use of Agency's or specialist's products, with periodic updates implemented over longer-time scales.

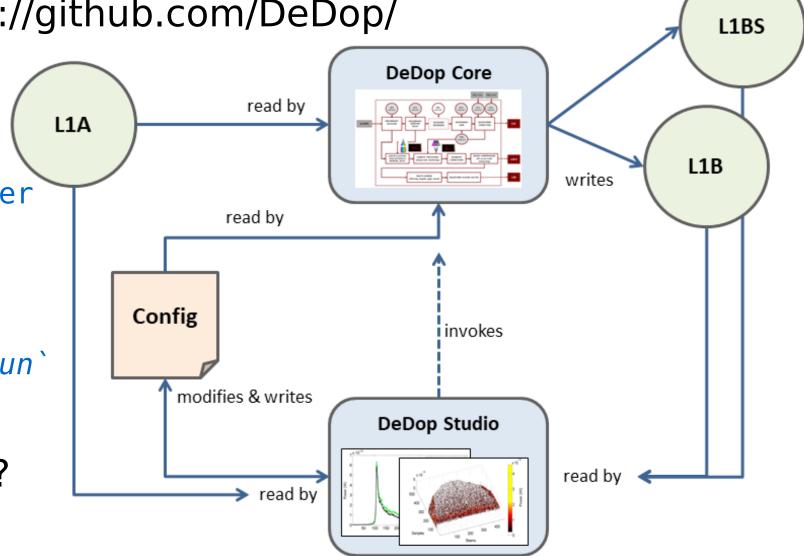
We present results from a case study on inland water in which the **DeDop Core** processor has been implemented on Sentinel-3A data over the Amazon river. The processor has been run using a custom configuration specifically designed for inland surfaces and improving the overall quality of the river water level measurements.

DeDop tools overview

DeDop tools include command line interface **DeDop Core** and GUI oriented application **DeDop Studio**. All tools share configuration files and input/output data setup.

Find them on GitHub: https://github.com/DeDop/

- Sample shell session:
- \$ dedop workspace add amazon
 \$ dedop config add inland_water
 # Then edit your config file
 \$ dedop input add files*.nc
- \$ dedop run scheduler

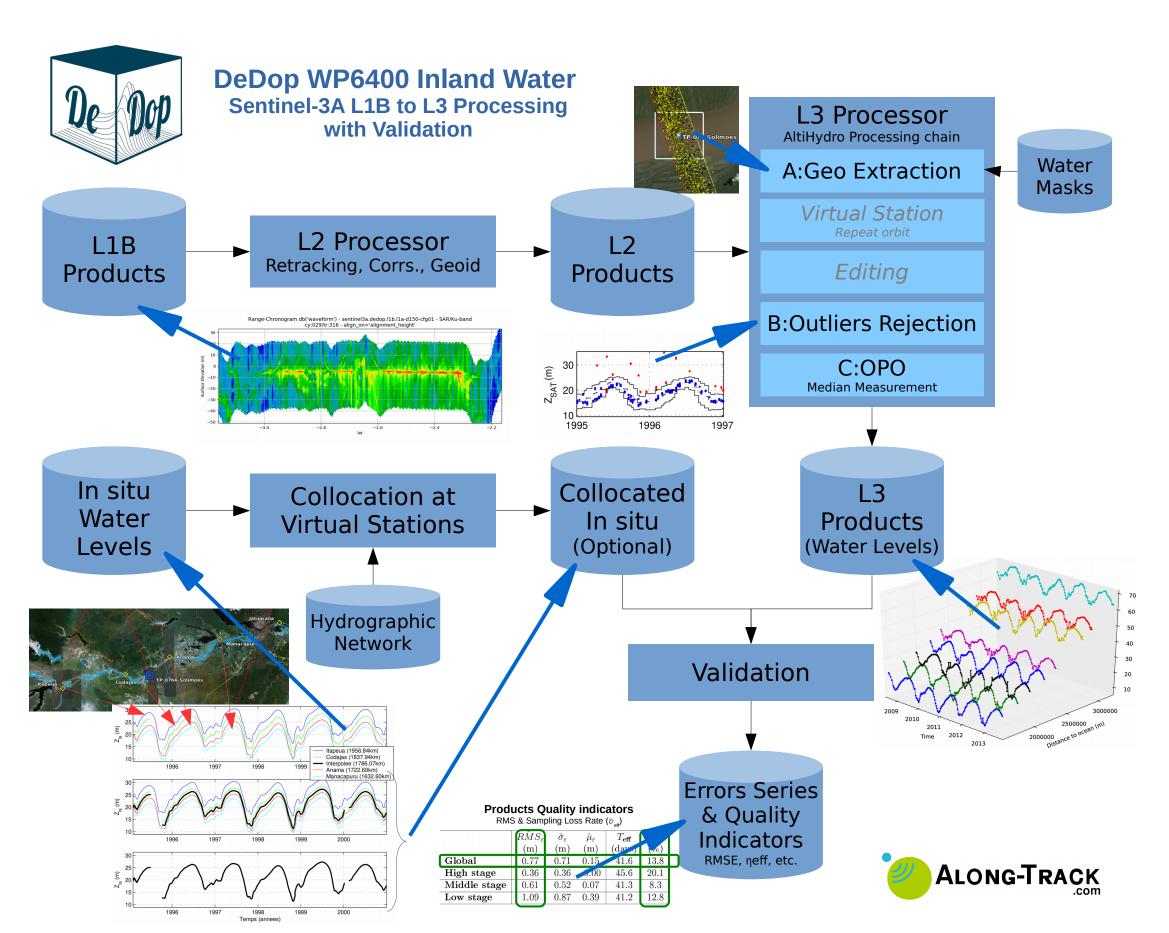


Or run on its own: `dedop run` \$ dedop output list

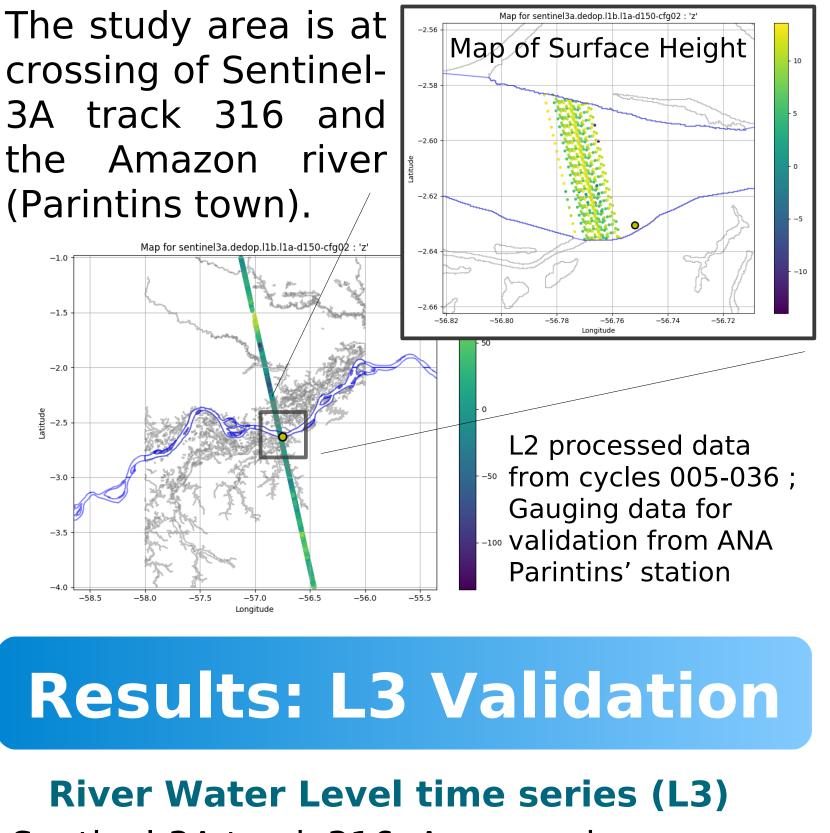
You're done ! Easy, isn't it ?

Processing stack : L2/L3Processors, Validation

In this study, we setup a complete L1A to L3 (water level time series) including the DeDop Core, basic L2 Processor (with Ice1 retracker, EIGEN6C4+DTU13 Geoid model and L2 corrections copied from Jason-3/GDR-d AVISO data) together with a L3 Processor (water masking, outliers Rejections, etc.) in order to estimate water level time series over the Amazon.



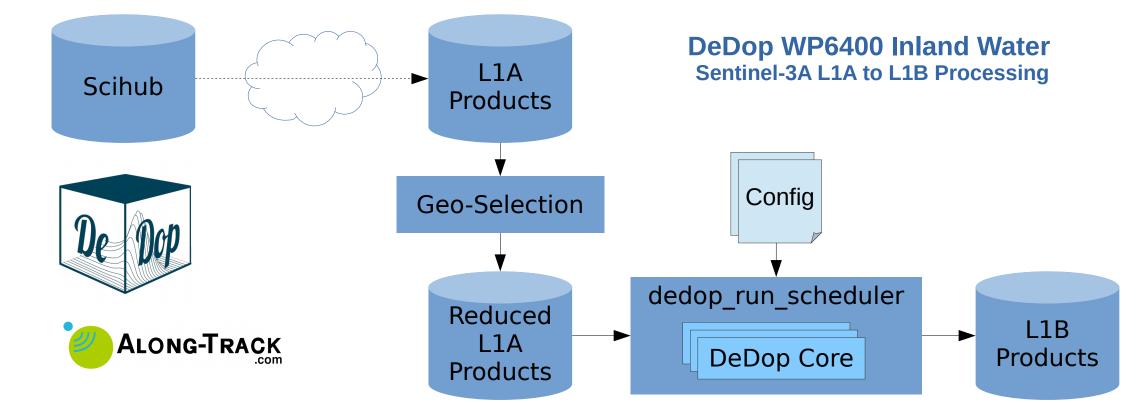
Case Study Area



Sentinel-3A track 316, Amazon river Parintins gauging data.

DeDop Core: L1BS/L1B Processing with dedop_run_scheduler

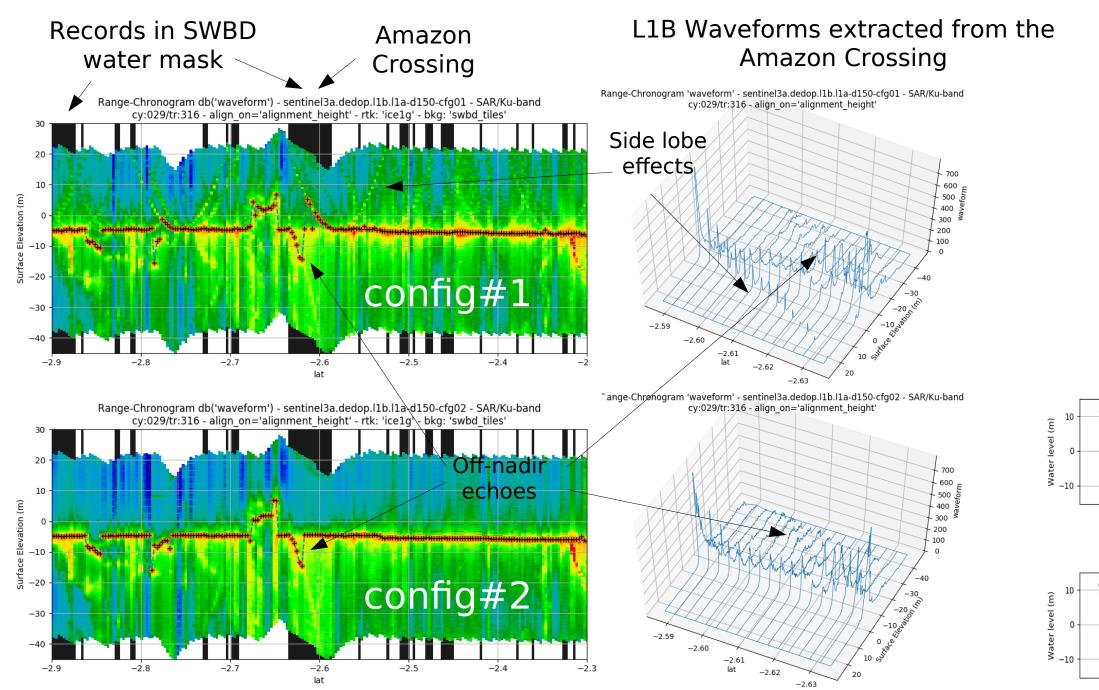
Sentinel-3A L1A product files are downloaded from scihub Copernicus portal. Since tracks are pole-to-pole, they have been truncated for latitudes matching the Amazon river location. DeDop Core has been run on them with companion tool **dedop_run_scheduler**. The outputs can be L1B with optional L1BS data product files:

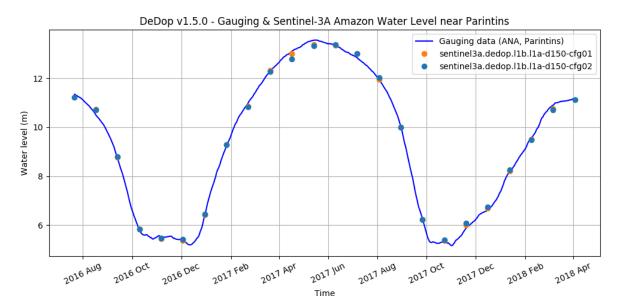


In order to make DeDop even more productive, ALONG-TRACK has developed a free and open source tool, named dedop_run_scheduler. This shell script allows to run several DeDop Core instances in parallel jobs (one input file processed per CPU core).

Results: L1B & L2 analysis

The whole processing chain (L1A \rightarrow L3) has been run for two DeDop configurations: basic config#1 and inland water config#2 with Hamming Windowing, Zero Padding Factor=2 and Exact focusing. Analysis on cycle 29 exhibits both off-nadir and side lobe effects on the resulting waveforms (L1B) for config#1 while config#2 improves the radargram/waveforms data.





Error quantification

L3 Water Level time series minus gauging data = Meas. Error \rightarrow Quality Indicators.

Outputs of intermediate steps A/B/C of the L3 processor have also been validated:

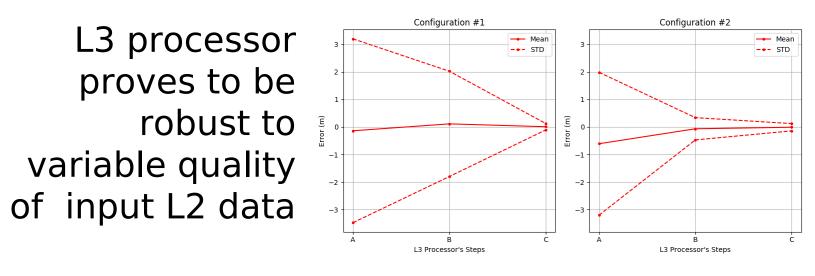


Table 3: Validation results for the L3 River Water Level time series. Detailed results for all steps of the L3 Processor, including: (A) L2 in water mask, (B) Outlier rejection and (C) final L3 for the two configurations #1 and #2.

| L3 Processing Step | DDP Config | Nb meas. | Mean±STD (m) | RMSE (m) | Sampling Loss Rate (%) |
|---|---------------|-------------|------------------|-------------|---|
| Step A . L2 – All records in Water Mask | #1 | 422 | -0.14±3.34 | 3.34 | N.A. (SLR defined for L3 data only) |
| | #2 | 422 | -0.61±2.60 | 2.66 | |
| Step B. L2 - After outliers | #1 | 380 | 0.11±1.91 | 1.92 | |
| rejection filter | #2 | 377 | -0.07 ± 0.40 | 0.41 | |
| Step C . L3 – Final: After OPO routine (median meas.) | #1 | 24 | 0.01±0.12 | 0.12 | 0% |
| | #2 | 24 | - 0.01±0.13 | 0.13 | 0% |

Go find **dedop_run_scheduler** on GitHub too:

https://github.com/nbercher-atk/dedop_run_scheduler

Conclusions

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- DeDop Core tool (v1.5.0) has been implemented using Sentinel-3A L1A product files from Copernicus/Scihub to produce L1B data for two delay-Doppler configurations
- An add-on job scheduler has been developed in order to run several DeDop Core instances in parallel along with improvement in DeDop source Code (closed GitHub Issue #31)
- A full L2 → L3 Processing stack has been added on top of DeDop Core, in order to produce River Water Level time series
- Validation of the L3 River Water Level has been done against gauging data
- As expected, results demonstrates the benefits of a customised delay-Doppler configuration vs. a basic (ocean-like) configuration

| | Outliers rejection filter - Time Series for 'sentinel3a.dedop.l1b.l1a-d150-cfg02' | OPO selection - Time Series for 'sentinel3a.dedop.l1b.l1a-d150-cfg02' | |
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| | | Input of Step B size in the second se | Input of Step B or z (z_icelg) |

• WARNING: Keep in mind that "Hamming windowing" destroys information that might be useful indeed...

What's to come?

• Test new processings approaches starting from L1BS data produced by DeDop Core

• Contribute to DeDop code & tools !!!

Acknowledgments

The ACA-DDP / DeDop project is founded by ESA

Altimetry data: Sentinel-3A L1A data from Copernicus https://scihub.copernicus.eu/dhus/. **Ancillary data:** In situ data from ANA (Brazil) ; in situ gauge stations leveling from Kosuth et al. (2006) ; Water mask are SWBD ShapeFiles from SRTM; Geoid model grids from GRGS & GFZ.

